

EROSION OF COASTAL DUNES DUE TO STORMS

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1. Introduction

Beach and dune erosion and associated mitigation measures are the most classical coastal engineering problems that are existing and have been studied extensively by many researchers (Dean 1973, Vellinga 1986, Kriebel et al. 1991, Dette and Uliczka 1987, Kraus et al. 1991, Steetzel, 1993, Larson et al., 2004).

Field experience over a long period of time in the coastal zone has led to the notion that storm waves cause sediment to move offshore while fair-weather waves and swell return the sediment shoreward. During high-energy conditions with breaking waves (storm cycles), the mean water level rises due to tide-induced forces, wind- and wave-induced setup and the beach and dune zones of the coast are heavily attacked by the incoming waves, usually resulting in erosion processes. When storm waves arrive at the beach, the crests break frequently, resulting in large volumes of water running up the beach face (see Figure 1A). Sand is dragged down the slope by the downrush causing erosion of the beach and dune faces and undermining of the dune toe. Part of the dune face may collapse when the local dune slope angle is larger than the equilibrium slope and lumps of sediment will slide downwards where it can be eroded again by wave-induced processes. The mass of sediment-laden water returning to the sea will drop its load at deeper water to form a bar. The sediments are carried in seaward direction by wave-induced near-bed return currents (undertow) and in longshore direction by wave-, wind- and tide-induced currents, which may feed locally generated rip currents. The undertow currents bring the sediments to the nearshore breaker bar systems, whereas the rip currents carry the sediments over longer distances to the edge of the surf zone. Three-dimensional flow patterns are dominant in the inner surf zone, whereas vertical circulations are dominant in the outer surf zone. These processes proceed relatively fast, as indicated by relatively large short-term variations (on the scale of events) of shoreline recession, formation of breaker bars and rip channels. During conditions with low non-breaking waves, onshore-directed transport processes related to wave-asymmetry and wave-induced streaming are dominant, usually resulting in accretion processes in the beach zone. A characteristic feature in the swash zone during low-energy conditions is the zig-zag movement of the sediment particles which is also known as beach drifting. In case of oblique wave incidence, the swash will run up the beach in the direction of wave propagation, but the backwash will move down the steepest slope under the influence of gravity. This latter movement usually is at a right angle to the shore. Sediment particles being moved by the swash and backwash will follow a zig-zag pattern along the shore parallel to the front of the breaking waves. The water carried in the uprush percolates partly through the sediment surface down to the water table at about mean sea level. This percolation reduces the volume of downwash, so causing the sand carried up to be deposited partly on the beach face. This build-up of the beach continues during low-energy conditions.

Herein, the attention is focussed on dune erosion processes during major storm events with relatively high surge levels. Detailed observations during recent dune erosion experiments in the large-scale Deltaflume of Delft Hydraulics (Delft Hydraulics, 2004, 2006a,b; Van Gent et al., 2008; Van Thiel de Vries et al., 2008) show the dominance of four processes:

- 1) the generation of strong wave impact forces at the steep dune face generating relatively high bed-shear stresses and hence erosion of sediment,
- 2) the production of large-scale turbulence due to the impact (wave collision) of incoming breaking waves and reflected broken waves generating fountains of water (see Figure 1B) and sediment resulting in a significant increase of the sediment carrying capacity of the offshore-directed return flows in the surf zone in front the dune,
- 3) the generation of low frequency waves in the surf zone (surf beat) due to spatial and temporal variation of the breaking point of the irregular high-frequency waves resulting in a spatial and temporal variation of the wave-induced set-up and
- 4) the regular sliding of the dune face when its has become too steep and the formation of a small bar at the toe of the dune face.

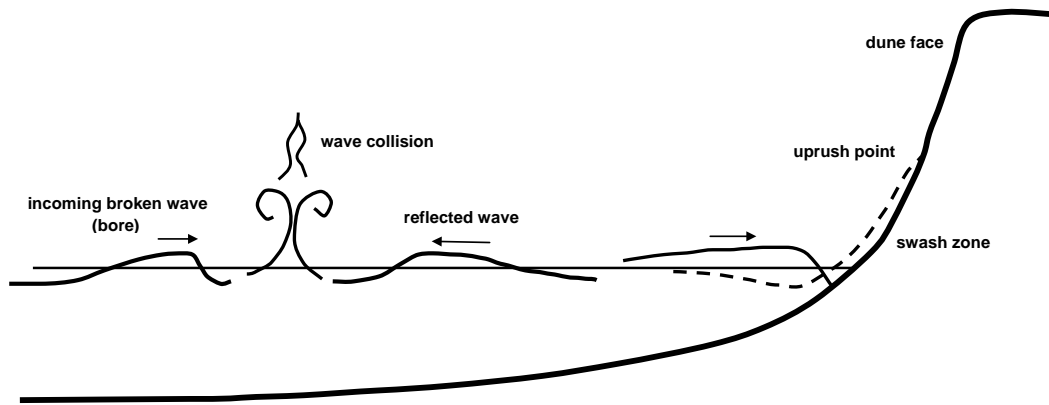


Figure 1A *Wave processes in the shallow surf zone in front of the dune*



Figure 1B *Impact of incoming and outgoing (reflected) waves in Deltaflume*

An overview of existing empirical models to estimate dune erosion is given by Larson et al. (2004) and will not be repeated herein. A semi-empirical model (S-beach) has been proposed by Larson and Kraus (1989). This model is based on equilibrium theory with limited description of the physical processes. A beach profile is assumed to attain an equilibrium shape if exposed to constant wave conditions for a sufficiently long time. An equilibrium profile ($h=Ax^{2/3}$ with x =cross-shore coordinate and A =shape parameter depending on bed material diameter) dissipates incident wave energy without significant net change in shape. The transport rate is related to the difference between the actual wave energy dissipation and the equilibrium wave energy dissipation along the equilibrium profile. The transport direction is determined from an empirical criterion. Steetzel (1993) has proposed a process-based mathematical model based on cross-shore wave propagation, wave shoaling, wave refraction and wave breaking. The output of the wave model is used to compute the local cross-shore sand transport rate. Bed level changes are determined from cross-shore gradients of the transport rate in a numerical loop system. A crucial process in the model of Steetzel (1993) is the erosion of sand in the dune face zone, which is done empirically by the use of a function which relates the relative magnitude of the transport rate in this zone to its position and level with respect to the last grid point of the wave model. Low-frequency effects (surf beat), the production of extra turbulence due to collapsing and colliding waves as well as dune face sliding are not taken into account explicitly. The model of Steetzel (1993) has been calibrated using measured data from experiments in the large-scale Deltaflume of Delft Hydraulics. Various field cases have been used to demonstrate the validity of the model for prototype conditions.

Van Thiel de Vries et al. (2008) have implemented the dominant dune erosion processes in the process-based DELFT3D-model including both low-frequency and high-frequency processes and the turbulent quantities. These modelling efforts show that the low-frequency effects (propagating bores) can be very well represented by a standard long wave model applied on the wave group time scale. The long waves, associated with the wave group varying short wave energy, can be solved with the surfbeat model (Reniers et al., 2004), which is implemented in DELFT3D-model. It is found that time series of the water surface elevations and the flow velocities in the inner surf and swash zone can be simulated accurately using a momentum conservative numerical scheme (Van Thiel de Vries et al., 2006). The model is being extended by including the wave breaking-induced turbulent quantities to represent the sediment suspension processes near the dune face. The interaction of simulated flows with the avalanching dune face is modeled in a relatively simple way, using separate critical slopes for wet and dry sand (Van Thiel de Vries and Reniers, 2008).

In this paper, the attention is focused on the cross-shore modelling of dune erosion using a process-based profile model (CROSMOR2007-model), which has been extended to include the afore-mentioned basic dune erosion processes. Mathematical model results for a range of conditions have been parameterized to develop a simplified dune erosion rule. Experimental results based on flume model tests have been used to verify the mathematical model.

2. Experimental results of dune erosion due to extreme storms

Experiments on dune erosion using scale models have been performed by Vellinga (1986) and Delft Hydraulics (2004, 2006a,b, 2007). The experimental data typically represent beach and dune erosion conditions along the Dutch North Sea coast during a very severe storm (design storm), which is herein defined as the Reference Case, see Table 1. The median sediment diameter along the Dutch coast is assumed to be 225 μm (0.225 mm). The high storm surge level (SSL) of 5 m above mean sea level (MSL) is assumed to be constant over a duration of 5 hours during the peak of the storm. This equivalent duration of 5 hours yields approximately the same overall dune erosion volume as a complete storm cycle with growing and waning phases (Vellinga, 1986). The offshore significant wave height is assumed to have a constant value of $H_{s,o} = 7.6$ m and the peak wave period is $T_p = 12$ s.

The vertical scale of the model tests was varied in the range of $n_h = 84$ to $n_h = 5$. The median sediment diameter was varied in the range of 95 to 225 μm ; thus: $n_{d50} = 2.4$ to 1. Large-scale experiments using a depth scale of $n_h = 5$ and an offshore wave height of 1.5 m have been done in the Deltaflume (length of 233 m, depth of 7m, width of 5 m), (Vellinga, 1986). Additional large scale tests with $n_h = 5$ and 6 have been performed in the Deltaflume to study the effect of the wave period on the dune erosion volume (Delft Hydraulics, 2006a,b, 2007).

| Parameter | Prototype conditions used by Vellinga (1986) |
|--|--|
| Offshore wave height (m) | 7.6 (Pierson and Moskowitz spectrum) |
| Offshore wave period (s) | 12 |
| Offshore water depth (m) | 21 m |
| Storm surge level above MSL (m) | +5 m NAP during 5 hours |
| Median sediment diameter (μm) | 225 |
| Median fall velocity (m/s) | 0.0267 |
| Water temperature ($^{\circ}\text{C}$) | 10 |
| Cross-shore profile | a) dune height at +15 m NAP, b) dune face with slope of 1 to 3 down to a level of +3 m NAP, c) slope of 1 to 20 between +3m and 0 m NAP, d) slope of 1 to 70 between 0 and -3 m NAP, e) slope of 1 to 180 seaward of -3 m NAP line |

(Remark: Mean Sea Level (MSL) is about equal to NAP)

Table 1 Parameters of Dutch coastal profile; Reference Case Storm

Figure 2 shows a plot of the scaled-up dune erosion area (data of Vellinga, 1986) as a function of time based on appropriate scaling laws (Van Rijn, 2008). Figure 3 shows the data of recent small-scale (Sflume) and large-scale flume tests (Dflume) performed at Delft Hydraulics (2004, 2006a,b, 2007) focussing on the effect of the wave period. The wave period was varied in the range of 12 to 18 s. Figure 3 shows that the dune erosion area above storm surge level after 5 hours increases with increasing wave period (about 18% for T increasing from 12 to 18 s).

Based on all data (Figs. 2 and 3), the dune erosion after 5 hours (in prototype values) is about $250 \pm 80 \text{ m}^3/\text{m}$ for the Reference Case with a wave period of $T=12 \text{ s}$ and the dune erosion after 40 hours is $450 \pm 150 \text{ m}^3/\text{m}$. Scale effects can be observed as the dune erosion area after 5 hours is much larger in the Deltaflume (about 25%) than that in the small-scale flume. The large-scale Deltaflume test of Vellinga (1986) shows slightly larger erosion areas (about 5% to 10%, Figure 2) after 5 and 10 hours than that of Delft Hydraulics (2006a,b, 2007), shown in Figure 3.

To evaluate the relative magnitude of scale errors, it is necessary to analyse prototype data of the Dutch coast related to a storm event. Storm erosion data (February 1953) is available for a coastal section between The Hague and Rotterdam (Delfland section; length of about 17 km). The data set comprises of cross-shore bed profiles measured a few days after the storm event (post-storm profiles) and bed profiles measured before the storm (pre-storm profiles measured about 3 to 6 months before the storm). The water level during the storm increased from +1.5 m to +3.9 m (above NAP; approx. mean sea level) over a period of about 30 hours. The maximum measured wave height is about $H_{s,0} = 6.3 \text{ m}$ at an offshore station. The local beach grain size is about 0.225 mm. The measured dune erosion area above the maximum storm surge level of +3.9 m varies in the range of 60 to $150 \text{ m}^3/\text{m}$ with a mean value of about $90 \text{ m}^3/\text{m}$ (Vellinga, 1986 and Steetzel, 1993).

Using empirical scaling laws (depth scale of 3.3 and a length scale of 4.6), the February 1953 storm including the time-varying storm surge level has been simulated by Vellinga (1986) in the Deltaflume of Delft Hydraulics. The measured dune erosion volume for this (distorted) laboratory test is about $120 \text{ m}^3/\text{m}$, which is about 30% larger than the mean observed value of $90 \text{ m}^3/\text{m}$ for field conditions. These results indicate that the scaling laws based on (distorted) 2D laboratory tests produce values which are somewhat too large for 3D field conditions. Given the lack of data for extreme storm conditions, a firm conclusion on the scale errors cannot yet be given.

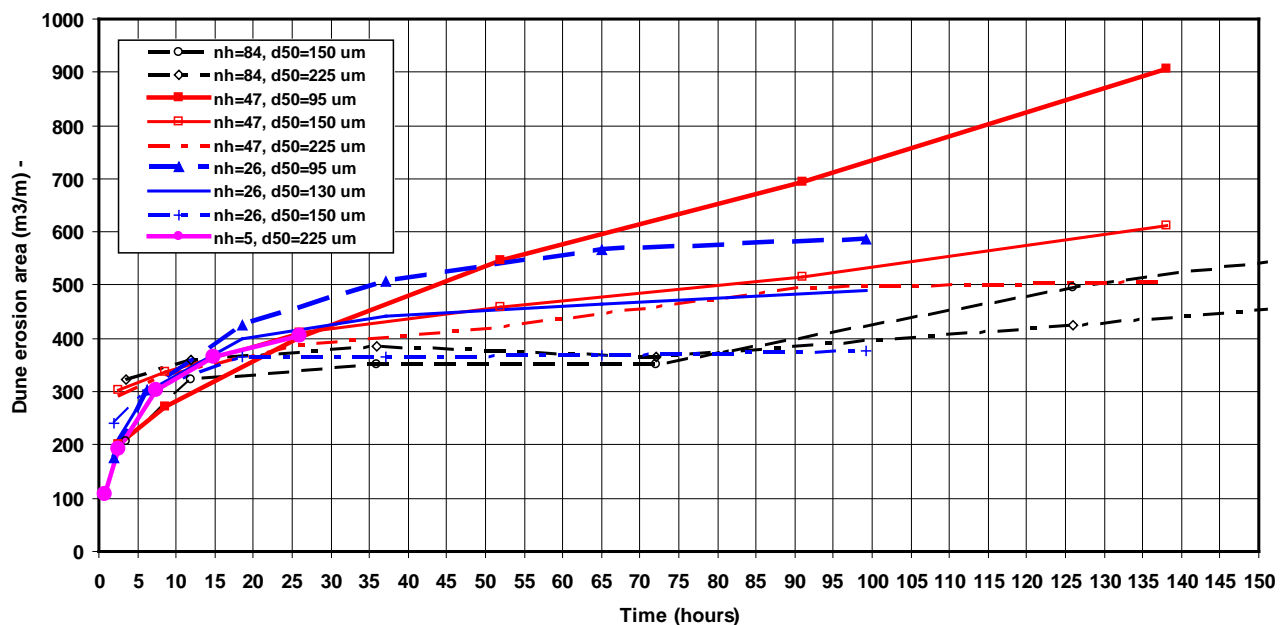


Figure 2 Dune erosion area (above SSL) as function of time (prototype values) based on data of Vellinga (1986)

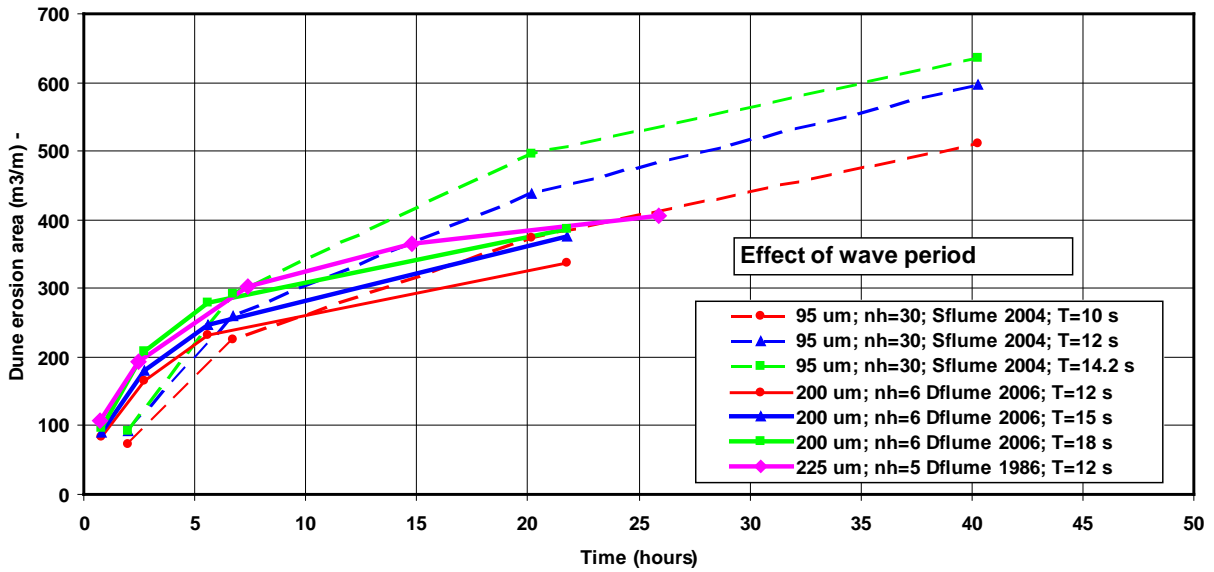


Figure 3 Dune erosion area (above SSL) as a function of time based on recent laboratory tests (Delft Hydraulics, 2004, 2006a,b)

3. Empirical DUROS+ method

The certified method to compute dune erosion in the Netherlands is known as the DUROS+ method.

The DUROS+method was initially developed by Vellinga (1986) based on many laboratory data sets (Figures 2 and 3) and later improved by others (Deltares,2007).

The eroded bed profile at the end of the design storm is described by (see Figure 4):

$$Y = 0.4714 (H_{o,s}/7.6) [(H_{o,s}/7.6)^{1.28} (12/T_p)^{0.45} (w_s/0.0268)^{0.56} x + 18]^{0.5} - 2 \quad (1)$$

$$X_{max} = 250 (H_{o,s}/7.6)^{1.28} (0.0268/w_s)^{0.56}$$

$$Y_{max} = [0.4714 \{250(12/T_p)^{0.45} + 18\}^{0.5} - 2] (H_{o,s}/7.6)$$

$${}^{10}\log(1/w_s) = 0.476({}^{10}\log d_{50})^2 + 2.18 {}^{10}\log(d_{50}) + 3.226 \quad (2)$$

with:

y= depth below the storm surge level (m),

x= distance from new dune foot origin (m),

$H_{o,s}$ = significant wave height at deep water (m),

T_p = peak wave period (s),

w_s = fall velocity of sand in seawater of 5° Celsius (m/s).

The origin ($x=0$, $y=0$) is defined as the intersection of Equation (1) and the storm surge level. The lower transition between the eroded bed profile and the original sea bed is assumed to have a slope of 1 to 12.5 (see Figure 4). The dune front through the origin ($x=0$, $y=0$) is assumed to have a slope of 1 to 1.

The origin should be shifted until $A_1 + A_2 = A_3$ (continuity of erosion and accretion).

The total dune area (A_{total}) above the storm surge level required to have a safe coastal dune is $A_{total} = A_1 + A_u + A_s$

with: A_u = area related to uncertainties involved (about $0.25A_1$) and A_s = area of safety profile (about $0.25A_1$).

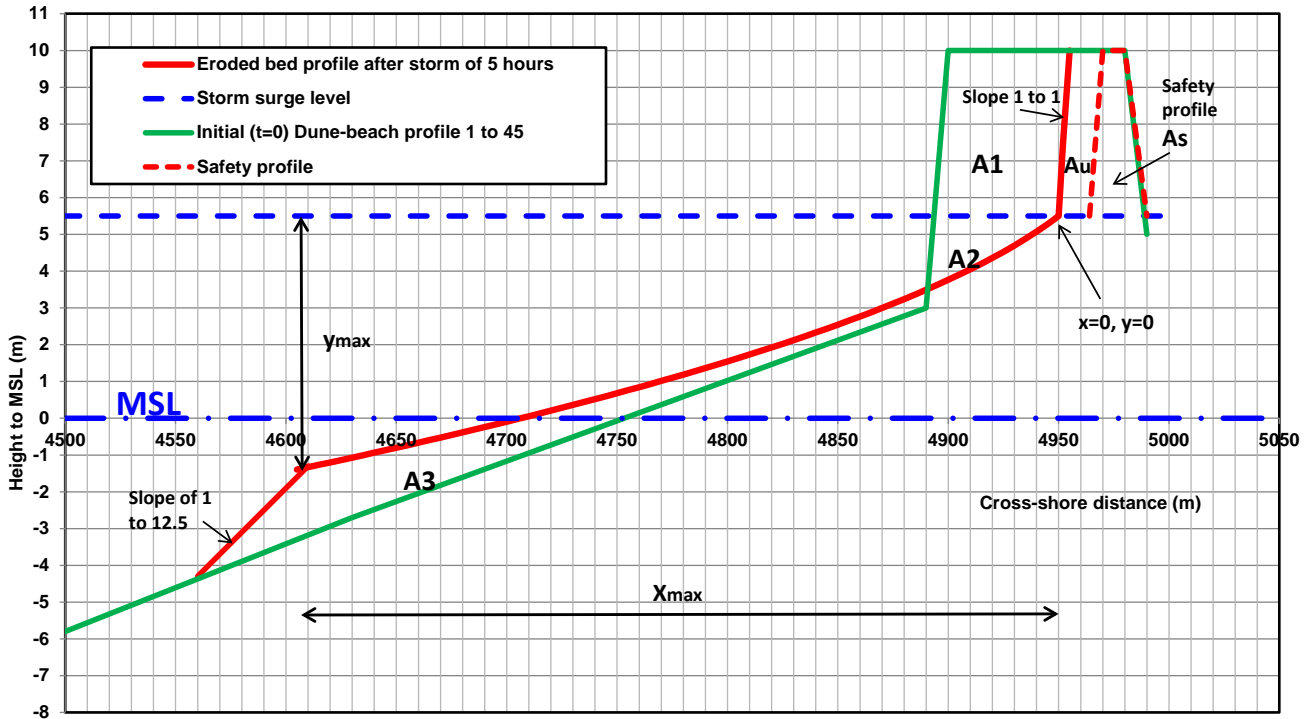


Figure 4 *Duros+ method;*

$H_{o,s} = 10 \text{ m}$, $T_p = 16.2 \text{ s}$, $SSL = 5.5 \text{ m}$, $d_{50} = 0.00025 \text{ m}$, $w_s = 0.0281 \text{ m/s}$, *Dune erosion* $A1 + A2 \cong 300 \text{ m}^3/\text{m}$

4. Cross-shore modelling of dune erosion using CROSMOR-model

The CROSMOR2007-model is an updated version of the CROSMOR2004-model (Van Rijn, 1997, 2006, 2007d). The model has been extensively validated by Van Rijn et al. (2003). The propagation and transformation of individual waves (wave by wave approach) along the cross-shore profile is described by a probabilistic model (Van Rijn and Wijnberg, 1994, 1996) solving the wave energy equation for each individual wave. The individual waves shoal until an empirical criterion for breaking is satisfied. The maximum wave height is given by $H_{max} = \gamma_{br} h$ with γ_{br} = breaking coefficient and h = local water depth. The default wave breaking coefficient is represented as a function of local wave steepness and bottom slope. The default breaking coefficient varies between 0.4 for a horizontal bottom and 0.8 for a very steep sloping bottom. The model can also be run with a constant breaking coefficient (input value). Wave height decay after breaking is modelled by using an energy dissipation method. Wave-induced set-up and set-down and breaking-associated longshore currents are also modelled. Laboratory and field data have been used to calibrate and to verify the model. Generally, the measured $H_{1/3}$ -wave heights are reasonably well represented by the model in all zones from deep water to the shallow surf zone. The fraction of breaking waves is reasonably well represented by the model in the upsloping zones of the bottom profile. Verification of the model results with respect to wave-induced longshore current velocities has shown reasonably good results for barred and non-barred profiles (Van Rijn et al., 2003; Van Rijn and Wijnberg, 1994, 1996). The complicated wave mechanics in the swash zone is not explicitly modelled, but taken into account in a schematized way. The limiting water depth of the last (process) grid point is set by the user of the model (input parameter; typical values of 0.1 to 0.2 m). Based on the input value, the model determines the last grid point by interpolation after each time step (variable number of grid points).

The cross-shore wave velocity asymmetry under shoaling and breaking waves is described by the semi-empirical method of Isobe and Horikawa (1982) with modified coefficients (Grasmeijer and Van Rijn, 1998; Grasmeijer, 2002). Near-bed streaming effects are modelled by semi-empirical expressions based on the work of Davies and Villaret (1997, 1998, 1999). The velocity due to low-frequency waves in the swash zone is also taken into account by an empirical method.

The depth-averaged return current (u_r) under the wave trough of each individual wave (summation over wave classes) is derived from linear mass transport and the water depth (h_t) under the trough. The mass transport is given by $0.125 g H^2/C$ with $C = (g h)^{0.5}$ = phase velocity in shallow water. The contribution of the rollers of broken waves to the mass transport and to the generation of longshore currents (Svendsen, 1984; Dally and Osiecki, 1994) is taken into account.

The sand transport of the CROSMOR2007-model is based on the TRANSPOR2004 sand transport formulations (Van Rijn, 2006, 2007a,b,c,d). The effect of the local cross-shore bed slope on the transport rate is taken into account (see Van Rijn, 1993, 2006).

The sand transport rate is determined for each wave (or wave class), based on the computed wave height, depth-averaged cross-shore and longshore velocities, orbital velocities, friction factors and sediment parameters. The net (averaged over the wave period) total sediment transport is obtained as the sum of the net bed load (q_b) and net suspended load (q_s) transport rates. The net bed-load transport rate is obtained by time-averaging (over the wave period) of the instantaneous transport rate using a formula-type of approach.

The net suspended load transport is obtained as the sum ($q_s = q_{s,c} + q_{s,w}$) of the current-related and the wave-related suspended transport components (Van Rijn, 1993, 2006, 2007). The current-related suspended load transport ($q_{s,c}$) is defined as the transport of sediment particles by the time-averaged (mean) current velocities (longshore currents, rip currents, undertow currents). The wave-related suspended sediment transport ($q_{s,w}$) is defined as the transport of suspended sediment particles by the oscillating fluid components (cross-shore orbital motion). The oscillatory or wave-related suspended load transport ($q_{s,w}$) has been implemented in the model, using the approach given by Houwman and Ruessink (1996). The method is described by Van Rijn (2006, 2007a,b,c,d). Computation of the wave-related and current-related suspended load transport components requires information of the time-averaged current velocity profile and sediment concentration profile. The convection-diffusion equation is applied to compute the time-averaged sediment concentration profile based on current-related and wave-related mixing. The bed-boundary condition is applied as a prescribed reference concentration based on the time-averaged bed-shear stress due to current and wave conditions. An additional calibration factor (sef-factor=suspension enhancement factor) acting on the time-averaged bed-shear stress and hence on the reference concentration in the shallow swash zone (dune erosion zone) in front of the dune face has been used to calibrate the model for dune erosion conditions; sef=1 yields the default model settings; a sef-value in the range of 2 to 3 is found (based on Deltaflume experiments 2005; see Figure 6) to be valid for the shallow surf zone in front of the dune face. The sef-factor is used to simulate the effects of wave collision and breaking in the shallow surf zone on the bed-shear stress and on the mixing capacity (increased turbulence) of the system resulting in a significant increase of the sand transport capacity. The shallow dune erosion zone is defined as the zone with a length scale of a few meters (of the order of the dune face length scale). To ensure a gradual transition from sef=1 outside the dune erosion zone, a linear transition is assumed to be present seaward of it.

Empirical functions are used to deal with wave-induced erosion and slope sliding at the dune front.

5. Modelling results of large-scale laboratory and field data

Large-scale Deltaflume data

New experiments have been carried out in the Deltaflume of Delft Hydraulics in the period October 2005 to March 2006, focussing on the effect of the wave period and type of wave spectrum on the dune erosion volumes for the Reference Case (see Section 2).

The bed material used is marine sand with $d_{10}=0.142$ mm, $d_{50}=0.2$ mm and $d_{90}=0.286$ mm. The fall velocity of the bed material has been determined by tests in a settling tube resulting in: $w_s=0.023$ m/s at a temperature of 9 °C. The still water level (SWL) representing the storm surge level (SSL) is set at 4.5 m above the original flume bottom. Irregular waves with a single topped Pierson-Moskowitz spectrum (single-topped) have been generated during 6 hours at the entrance of the flume during most tests. A double-topped wave spectrum has been used in Test T16. Most tests have been repeated twice to perform detailed process measurements during the second test. The eroded profiles of three tests after 6 hours are shown in Figure 6. The profile shows erosion above a level of -0.2 m (to SWL); deposition can be observed offshore of the -0.2 m bed level over a length of about 30 m. The erosion area increases by about 15% (based on T01 and T03) in the case of a larger wave period (from 4.9 s to 7.4 s).

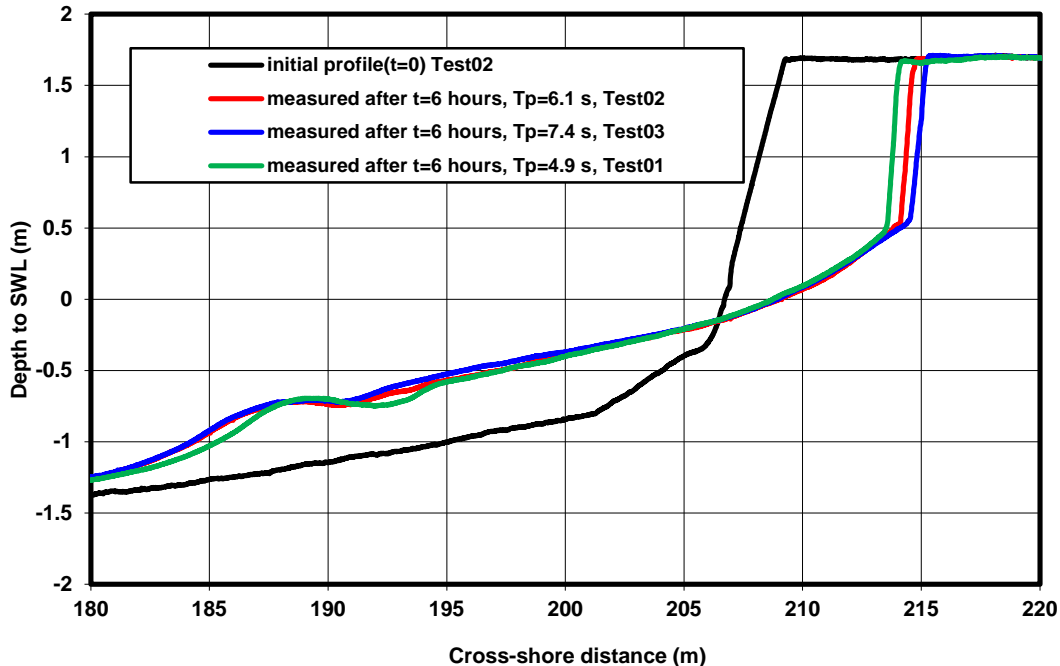


Figure 5 Measured bed profiles after 6 hours for Tests T01, T02 and T03

The dune erosion profiles of Test T01 have been used to calibrate the sef -parameter of the CROSMOR2007-model. The sef -parameter is the suspension enhancement factor (multiplication factor) acting on the time-averaged bed-shear stress and hence on the reference concentration and the sediment mixing coefficient in the shallow dune erosion zone; $sef=1$ refers to the default transport model.

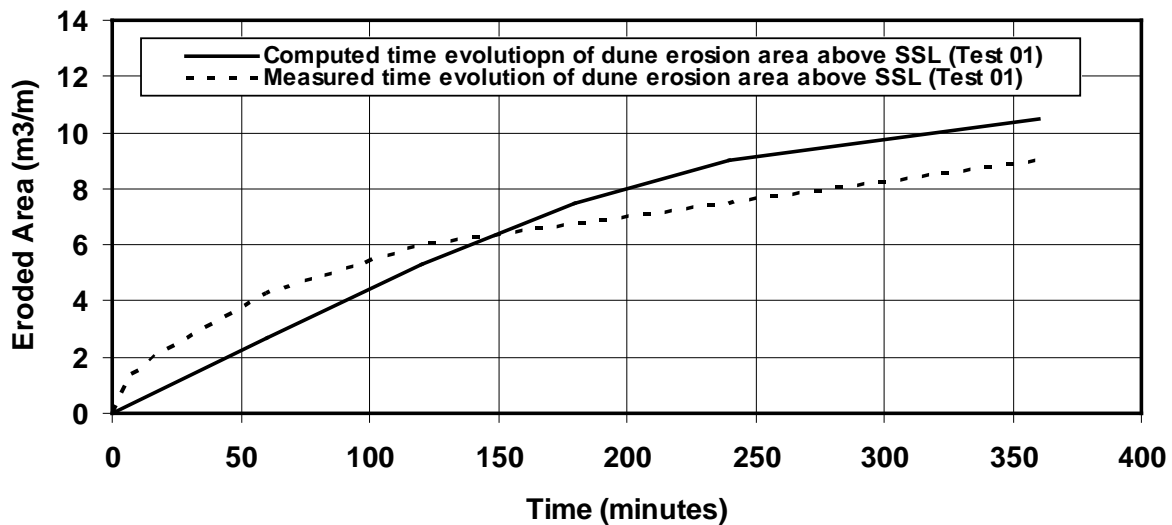


Figure 6 Time development of computed and measured dune erosion area above SSL for Test T01

The best overall agreement between computed and measured dune face recession (shoreline recession) after 6 hours is found for $\text{sef}=2.5$ with the long wave effect included.

Figure 6 shows the computed and measured dune erosion area above storm surge level (SSL) as a function of time. A significant difference between computed and measured results can be observed. The measured dune erosion area is much larger (about 50%) than the computed value in the initial phase (time < 150 minutes) of the dune erosion process. This initial effect with relatively large erosion values cannot be represented by the model. Almost half of the total dune erosion is produced in the first 60 minutes of the total test duration of 360 minutes (6 hours). At the end of the test duration the measured and computed values are within 15% of each other; the computed values are somewhat larger than the measured values.

February 1953 storm, The Netherlands

The model has been used to simulate the February-1953 storm which attacked the Dutch coast and particularly the south-west part of The Netherlands. The initial bed profile consists of four line sections (Figure 7).

The beach slope is 1 to 20 and the dune slope is set to about 1 to 1 (angle of 45 degrees). The dune height is set to 12 m above MSL. The dune toe is at +3 m above MSL. The storm surge level (SSL) varies between +1.5 and +3.9 m above MSL over a period of 30 hours (storm duration). The maximum SSL occurs after 14 hours and remains constant for about 2 hours. The wave height at deep water varies between 4.9 and 6.3 m; the peak wave period varies between 8.8 and 10 s. Measured erosion volumes in the Delfland region (south-west part of the Holland coast) are in the range of 60 to 150 m³/m with a mean value of 90 m³/m, which is equivalent to a dune recession of about 10 m above the dune toe level.

Model runs have been made using a bed material diameter of 0.2 and 0.25 mm. The wave height distribution is represented by a Rayleigh-type distribution schematized into 6 wave classes for each wave condition. The computed dune erosion volume above the maximum SSL varies between 100 m³/m for 0.25 mm and 120 m³/m for 0.2 mm, which is somewhat larger than the observed values. The maximum horizontal dune recession is about 13 m for 0.2 mm. Computed bed profiles are shown in Figure 7.

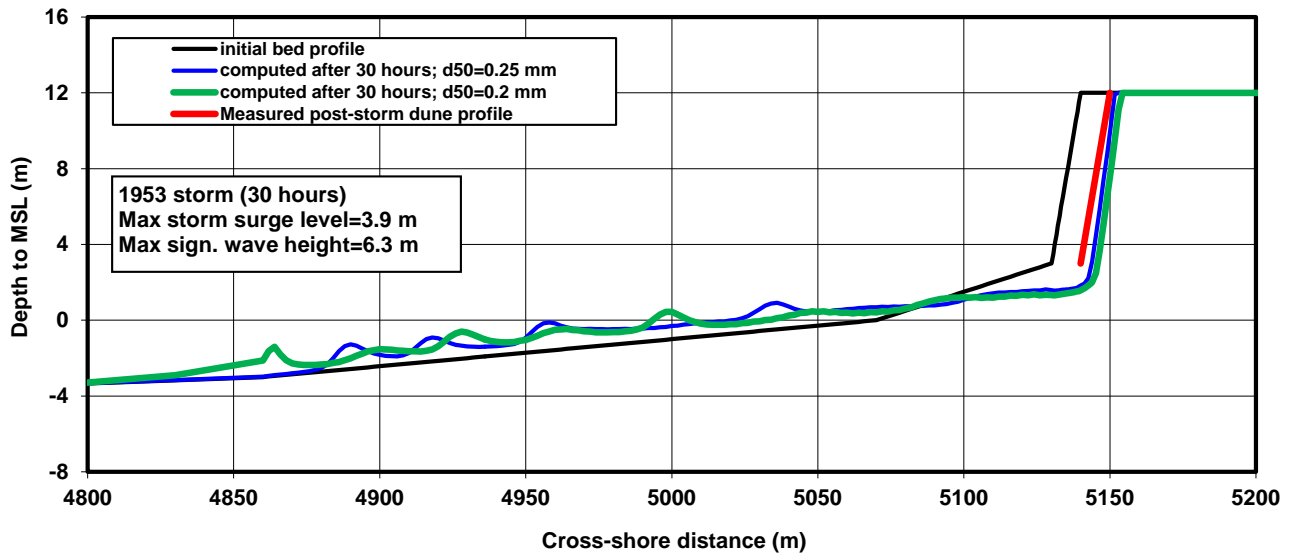


Figure 7 Measured and computed bed profiles for February 1953 storm, The Netherlands

6. Sensitivity study and development of simplified dune erosion rule

The CROSMOR-model has been used to study the effect of various key parameters on the computed dune erosion after 5 hours (duration of standard storm) for the Reference Case:

- effect of storm surge level in the range of 2 to 8 m;
- effect of offshore wave height in the range of 3.8 to 10 m;
- effect of peak wave period in the range of 9 to 18 s;
- effect of wave angle in the range of 0 to 30 degrees;
- effect of bed material size in the range of 0.15 to 0.3 mm;
- effect of steeper and milder beach profile.

The Reference Case is defined in Table 1 as proposed by Vellinga (1986). The initial profile consists of four sections. The beach slope is 1 to 20 and the dune slope is 1 to 3 (angle of about 20°). The dune height is set to 15 m above MSL. The dune toe is at +3 m above MSL. The storm surge level is set to +5 m. The duration of a standard storm is set to 5 hours. The wave height at deep water is set to 7.6 m. The peak wave period is 12 s. The forcing parameters are constant in time; the growing and decaying phases of the storm have been neglected. The wave height distribution of the CROSMOR-model is represented by a Rayleigh-type distribution schematized into 6 wave classes. The computed dune erosion volumes above the storm surge level (+5 m to MSL) for the Reference Case is 170 m³/m after 5 hours, which is considerably smaller than the value of 250 m³/m based on physical scale model results (see Section 2). Upscaling of the laboratory results to field conditions may introduce scaling errors. Furthermore, scale errors may also be introduced by schematization of 3D field conditions to 2D flume conditions. The 2D laboratory model results of the 3D prototype dune erosion caused by the February 1953 storm show an over-estimation of the measured prototype dune erosion by about 30% (see Section 2).

Figure 8 shows the effect of the storm surge level (in the range of $S=2$ to 8 m above mean sea level) on the bed profile after 5 hours. The reference storm surge level is $S_{ref}=5$ m above mean sea level. The dune erosion strongly increases with increasing storm surge level.

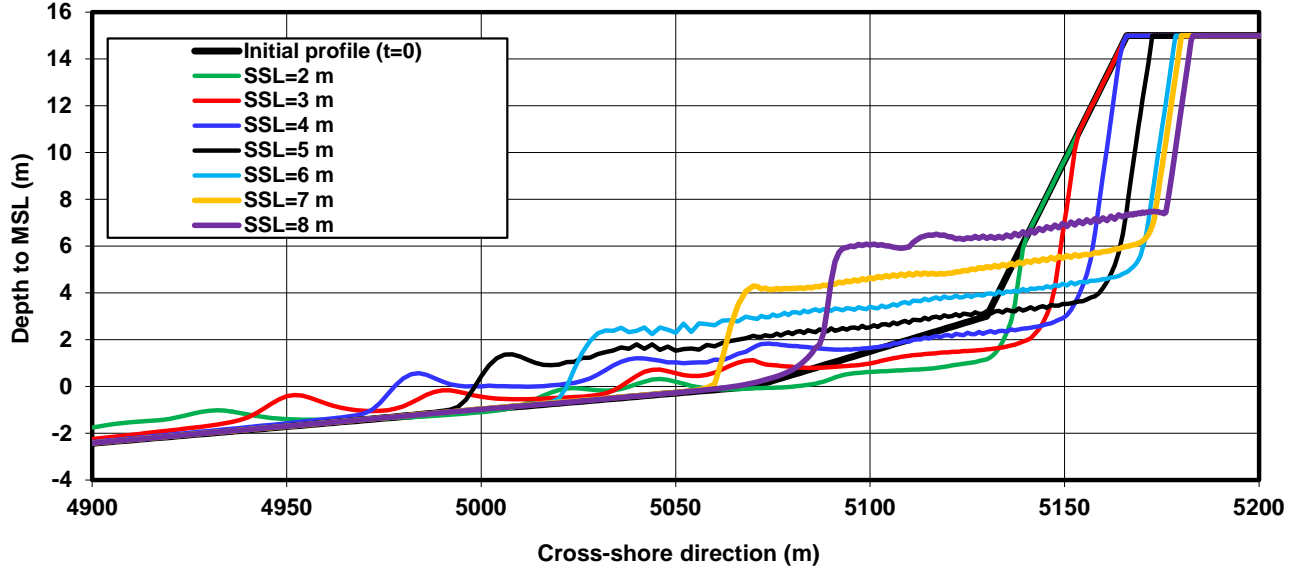


Figure 8 Effect of storm surge level on computed bed profile after 5 hours for Reference Case

7. Simplified dune erosion rule (DUNERULE-model)

The results of the sensitivity study based on the CROSMOR-model runs have been used to develop a simplified dune erosion rule (DUNERULE-model), as follows (see Figure 9):

$$A_{d,t=5} = A_{d,ref} (d_{50,ref}/d_{50})^{\alpha_1} (S/S_{ref})^{\alpha_2} (H_{s,o}/H_{s,o,ref})^{\alpha_3} (T_p/T_{p,ref})^{\alpha_4} (\tan\beta/\tan\beta_{ref})^{\alpha_5} (1+\theta_o/100)^{\alpha_6} \quad (3)$$

with:

$A_{d,t=5}$ = dune erosion area above storm surge level after 5 hours (m^3/m),

$A_{d,ref}$ = dune erosion area above S storm surge level after 5 hours in Reference Case= 170 (m^3/m),

S = storm surge level above mean sea level (m),

S_{ref} = storm surge level above mean sea level in Reference Case= 5 (m),

$H_{s,o}$ = offshore significant wave height (m),

$H_{s,o,ref}$ = offshore significant wave height in Reference Case= 7.6 (m),

T_p = peak wave period (s),

$T_{p,ref}$ = peak wave period (s) in Reference Case= 12 (s),

d_{50} = median bed material diameter (m),

$d_{50,ref}$ = median bed material diameter in Reference Case= 0.000225 (m),

$\tan\beta$ = coastal slope gradient defined as the slope between the -3 m depth contour (below mean sea level) and the dune toe (+3 m),

$\tan\beta_{ref}$ = coastal slope gradient defined as the slope between the -3 m depth contour and the dune toe (+3 m) for the Reference Case= 0.0222 (1 to 45),

θ_o = offshore wave incidence angle to coast normal (degrees),

α_1 = exponent=1.3,

α_2 = exponent=1.3 for $S < S_{ref}$ and $\alpha_2=0.5$ for $S > S_{ref}$,

$\alpha_3 = \alpha_4 = \alpha_6 = 0.5$ (exponents),

α_5 = exponent=0.3.

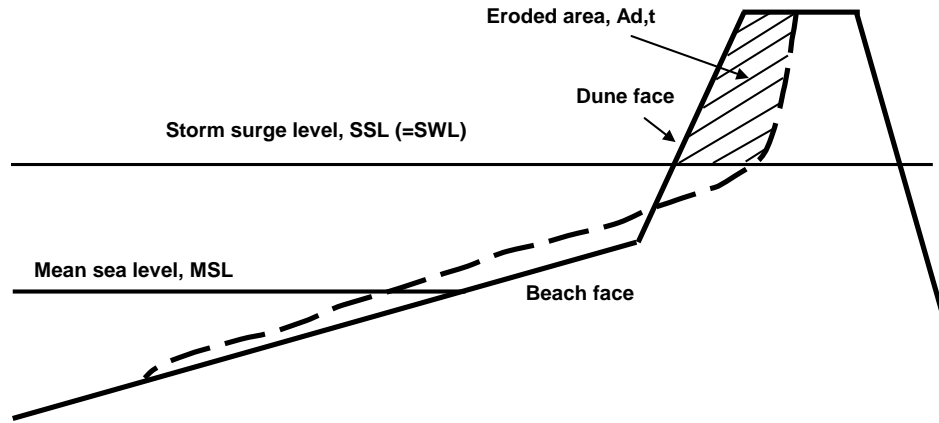


Figure 9 Sketch of dune erosion

Equation (3) yields zero erosion for $S=0$ (no storm surge set-up).

The average horizontal dune recession (R_d) can be estimated from:

$$R_d = A_d / (h_d - S) \quad (4)$$

The maximum horizontal dune recession ($R_{d,max}$) at storm surge level can be estimated from:

$$R_{d,max} \cong 1.5 R_d \quad (5)$$

with:

R_d = average horizontal dune recession (m),

$R_{d,max}$ = maximum horizontal dune recession at storm surge level (m),

h_d = height of dune crest above mean sea level (m).

The time development over 100 hours can be estimated from:

$$A_{d,t} = A_{d,t=5} (t/t_{ref})^{\alpha_6} \quad (6)$$

with:

t = time in hours ($t_{ref} = 5$ hours),

α_6 = exponent = 0.5 for $t < t_{ref}$ and 0.2 for $t > t_{ref}$.

Basically, the proposed method produces dune erosion values with respect to a defined Reference Case (storm with a constant storm surge level, wave height and duration of 5 hours). According to the CROSMOR-model, the dune erosion area above storm surge level in the Reference Case is approximately $A_{d,ref} = 170 \text{ m}^3/\text{m}$. According to the experimental values (Vellinga, 1986), this value is about $250 \text{ m}^3/\text{m}$. This range defines the uncertainty range. The storm surge level (S) above mean sea level and the bed material diameter (d_{50}) are the most influential parameters. Equation (3) is especially suitable for probabilistic computations to represent the natural variations of the controlling parameters.

Example 1

Figure 10 shows plots of the dune erosion area (above the storm surge level) after 5 hours as a function of the sediment size and the storm surge level for two wave climates (North Sea and Mediterranean) based on the simplified model of Van Rijn (Equation 3) for the case of waves normal to the coast.

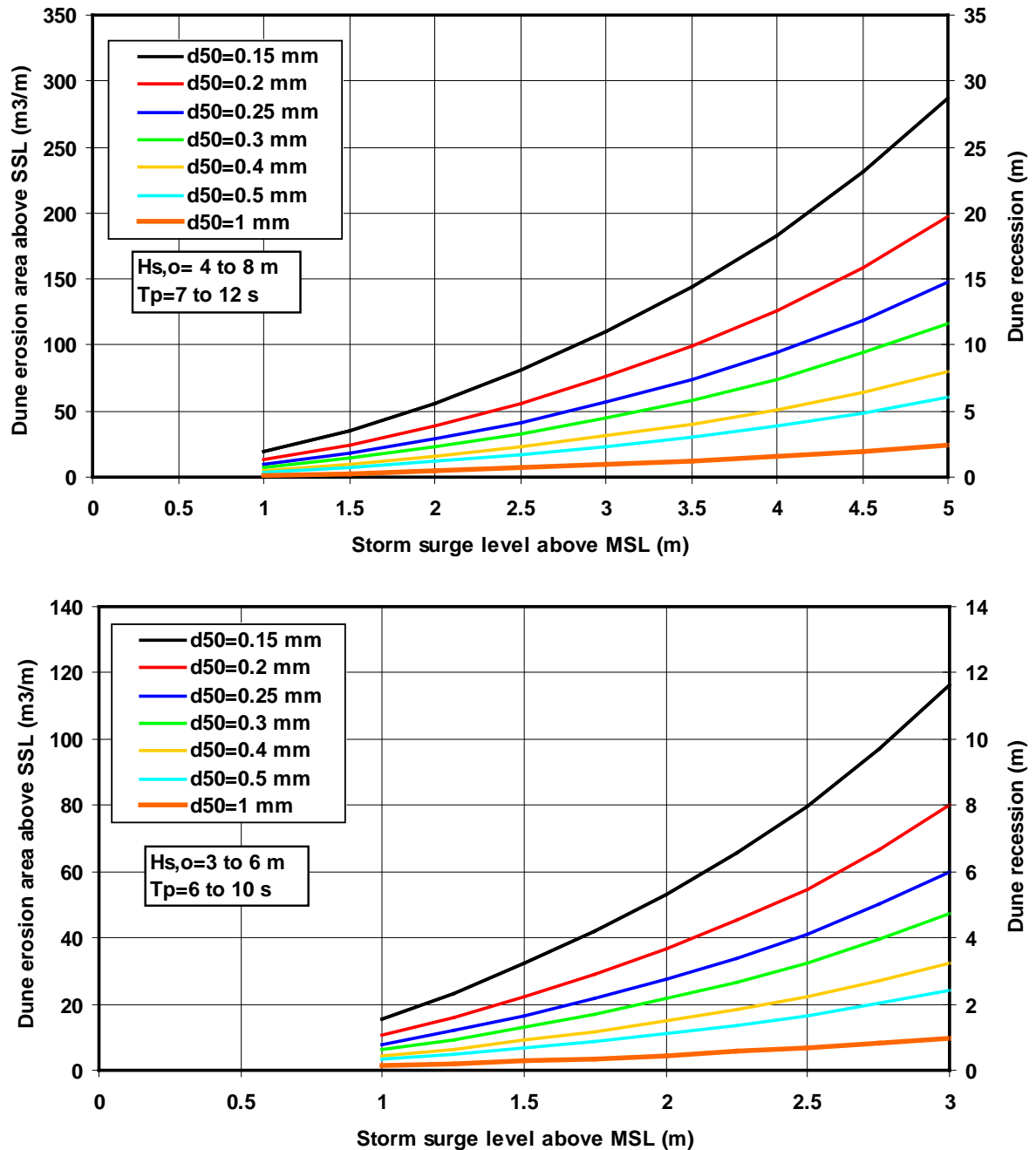


Figure 10 Dune erosion after 5 hours during a storm event as function of sediment size and storm surge level for two wave climates: North Sea (upper) and Mediterranean (lower); dune recession based on dune height of 10 m above SSL

The significant offshore wave height in the North Sea is assumed to vary between 4 and 8 m for surge levels between 1 and 5 m above mean sea level (MSL). Dune erosion after 5 hours is largest for relatively fine sediments (0.15 mm) and reduces rapidly for coarser sediments. Dune erosion of gravel (1 mm) is only 15% of that of fine sand (0.15 mm). The shoreline recession (E) due to dune erosion can be estimated from $E=A/h$ with A = dune erosion area above storm surge level SSL and h = dune height above the storm surge level.

Figure 10 shows dune recession values (axis on right side of plot) based on a dune height of 10 m above SSL. Dune recession values are twice as large for dune height of 5 m.

Dune erosion is very much related to extreme events with high surge levels including tidal effects. Extreme storms have a large return period. For example, a North Sea storm with a surge level of 5 m above mean sea level has, on average, a return period of about 10,000 years (so once in 10,000 years), but it can happen tomorrow. The return period of a surge level of only 2 m is 1 year; so, once every year. The computed dune erosion values after 5 hours are of the order of 20 m³/m for a surge level of 1 m and up to 300 m³/m ($d_{50}=0.15$ mm) for a large surge level of 5 m, see Figure 10.

To withstand an extreme event with a surge level of 5 m above mean sea level, the dune row fronting the sea should have a minimum width of the order of 50 m. In 'normal' conditions with two or three events per year with surge levels between 1 and 2 m per year, the total annual dune erosion may be as large as 50 m³/m/year locally along the sandy North Sea coasts. Most of the eroded dune sand will be deposited on the beach from where it can be returned to the dune front by wind-induced forces or carried away by cross-shore and longshore currents. Dune accretion at the dune front due to wind effects is of the order of 10 to 20 m³/m/year and is generally not sufficient to compensate dune erosion on the annual time scale by natural processes. Thus, dune erosion generally leads to a permanent loss of sand which can only be compensated by artificial nourishment (dune restoration).

Example 2

The following storm values are used to compute the dune erosion under minor storms:

$S=4$ m (storm surge level above MSL), $H_{s,0}=5$ m (significant wave height at deep water), $T_p=10$ s (peak wave period), $d_{50}=0.0002$ m (bed material diameter), $\alpha_0=20^\circ$ (wave incidence angle at deep water), $h_d=15$ m (dune height), $\tan\beta=0.02$ (beach slope), yielding:

$$A_d = 170 (0.000225/0.0002)^{1.3} (4/5)^{1.3} (5/7.6)^{0.5} (10/12)^{0.5} (0.02/0.0222)^{0.3} (1+20/100)^{0.5} = 115 \text{ m}^3/\text{m} \text{ after 5 hours.}$$

$$A_d = 82 \text{ m}^3/\text{m} \text{ after 2.5 hours and } 135 \text{ m}^3/\text{m} \text{ after 10 hours.}$$

$$R_d = 115/(15-4)=10.5 \text{ m after 5 hours; } 7.5 \text{ after 2.5 hours and } 12.5 \text{ m after 10 hours.}$$

$$R_{d,max} = 16 \text{ m after 5 hours; } 11 \text{ m after 2.5 hours and } 19 \text{ m after 10 hours.}$$

Example 3

Equation (3) is most valid for dune erosion under major storms, but also yields realistic results for minor storm events.

Data are taken from the storm erosion field database summarized by Birkemeier et al. (1988), (see also Larson et al., 2004). The data have been clustered into 10 cases, shown in Table 2. The bed material diameter at these beaches varies in the range of $d_{50}=0.3$ to 0.5 mm. The coastal slope is taken as $\tan\beta=0.0222$.

| Field site | Wave height (m) | Wave period (s) | Surge level (m) | Surge duration (hours) | Measured dune erosion volume (m ³ /m) | Predicted dune erosion volume (m ³ /m) |
|------------|--------------------|--------------------|--------------------|---------------------------|---|--|
| LBI | 2.6 | 9 | 1.5 | 14 | 15±7 | 10 |
| AC, LB | 2.6 | 8 | 1.5 | 14 | 6±5 | 10 |
| LB | 3.4 | 8 | 1.4 | 24 | 8±4 | 11 |
| LBI | 1.9 | 8 | 1.5 | 36 | 27±7 | 10 |
| LB | 2.1 | 7 | 1.5 | 36 | 10±3 | 9 |
| NB | 2.4 | 8 | 2 | 10 | 25±3 | 15 |
| NB | 3.6 | 9.5 | 2.5 | 12 | 27±10 | 24 |
| MB, WB, JB | 3.8 | 10.5 | 2 | 11 | 10±5 | 18 |
| AC, LB | 3.0 | 8 | 1.8 | 10 | 5±3 | 12 |
| LB | 1.8 | 10 | 1.5 | 12 | 7±4 | 9 |

NB= Nauset Beach, MB=Misquamicut Beach, WB=Westhampton Beach, JB= Jones Beach, LBI=Long Beach Island, AC=Atlantic City, LB=Ludlam Beach

Table 2 *Dune erosion volumes during minor storm events along various USA-beaches*

Equations (3) and (6) have been used to predict the dune erosion volumes at these beaches. The wave incidence angle is assumed to be zero (normal to coast). The bed material diameter is set to 0.4 mm for all cases.

For example, the dune erosion at Nauset Beach according to Equation (3) is:

$$A_{d,t=5} = 170 (0.225/0.4)^{1.3} (2.5/5)^{1.3} (3.6/7.6)^{0.5} (1)^{0.3} (9.5/12)^{0.5} = 20 \text{ m}^3/\text{m} \text{ after 5 hours.}$$

Equation (6) yields the dune erosion volume after 12 hours: $A_{d,t=12} = 20 (12/5)^{0.2} = 24 \text{ m}^3/\text{m}$.

The measured value is 27 m³/m.

The predicted dune erosion is within the variation range for 6 cases; systematically too large for 2 cases and systematically too small for 2 cases.

8. Conclusions

This paper presents results of experimental and mathematical modelling of beach and dune erosion under storm events.

Re-analysis of the experimental results on dune erosion in flumes (work of Vellinga, 1986 and others) show that the dune erosion for the Reference Case Storm (Table 1) is about 250 m³/m.

Laboratory flume results of the dune erosion caused by the February 1953 storm (including the time-varying storm surge level) show that the dune erosion volume for the (distorted) laboratory test is about 30% larger than the mean (observed) value for field conditions (about 90 m³/m).

Dune erosion caused by wave impact has been modelled by a cross-shore profile model (CROSMOR-model), which is based on a 'wave by wave' modelling approach solving the wave energy equation for each individual wave. The individual waves shoal until an empirical criterion for breaking is satisfied. Wave height decay after breaking is modelled by using an energy dissipation method. Wave-induced set-up and set-down and breaking-associated longshore currents are also modelled. The model has been applied to the recent Deltaflume experiments on dune erosion. The three main processes affecting dune erosion have been taken into account: the generation of low-frequency effects, the production of extra turbulence due to wave breaking and wave collision

and the sliding of the dune face due to wave impact. The inclusion of low-frequency effects only marginally affects the dune erosion. The two most influential model parameters are the suspension enhancement factor (sef) which represents the effect of extra turbulence in the dune erosion zone and the wave breaking coefficient, which determines the maximum wave height. The suspension enhancement factor (sef) is required to model the increase of the sand transport capacity in the shallow surf zone in front of the dune face, which is supposed to be primarily caused by large-scale turbulence generation due to wave collision effects. The Deltaflume test results can be reasonably well simulated by using $sef=2.5$ ($sef=1$ means no effect).

The calibrated CROSMOR-model (based on Deltaflume results) can very well simulate the observed dune erosion above the storm surge level during storm events in small-scale facilities, large-scale facilities and in the prototype (1953 storm in The Netherlands) using the same model settings. The dune erosion above storm surge level after 5 hours generally is slightly over-estimated. The erosion below the storm surge level is considerably over-estimated by the model.

Based on the results of a detailed sensitivity study, the two most influential parameters are found to be the storm surge level (above mean sea level) and the bed material diameter. Dune erosion increases with increasing storm surge level (S) and with decreasing bed material diameter (d_{50}). The wave period also has a marked influence. Dune erosion increases with increasing wave period. The wave spectrum has no significant effect on dune erosion.

The relative changes of the erosion parameters (erosion area above storm surge level) caused by variation of physical parameters such as wave period, wave spectrum and bed material size are of the same order as those caused by variation of basic model parameters (wave breaking coefficient, roller model, swash zone parameters).

Application of the CROSMOR-model to the prototype Reference Case as defined by Vellinga (1986) yields a dune erosion volume of about $170 \text{ m}^3/\text{m}$, which is considerably smaller than the value of about $250 \text{ m}^3/\text{m}$ based on laboratory wave flume results. This discrepancy may be caused by upscaling errors (using available scaling laws) of laboratory test results to prototype conditions and by mathematical modelling errors.

A sensitivity study for the Reference Case shows that the most influential parameters are the storm surge level and the sand diameter. The wave period and the offshore wave incidence angle have a smaller effect. Dune erosion increases slightly with increasing wave period and increasing wave angle (oblique waves).

The mathematical model results have been used to develop a new dune erosion rule (DUNERULE-model). This dune erosion rule estimates the dune erosion with respect to a base Reference Case, which represents a storm of 5 hours duration with a constant wave height of 7.6 m (period of 12 s; normal to coast), bed material diameter of 0.225 mm and storm surge level of +5 m (above mean sea level). The computed dune erosion (above storm surge level) of the base Reference Case is $170 \text{ m}^3/\text{m}$ after 5 hours. The most influential parameters are the storm surge level (S) and bed material diameter (d_{50}). Dune erosion decreases for smaller storm surge levels, smaller wave heights, smaller wave periods, shorter storm duration and coarser sand. The new dune erosion rule is most valid for dune erosion under major storms, but also yields realistic results for minor storm events based on a comparison with measured data from USA-beaches.

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